

Figure 1: Depth first search.

Explorative behavior:

depth first search.

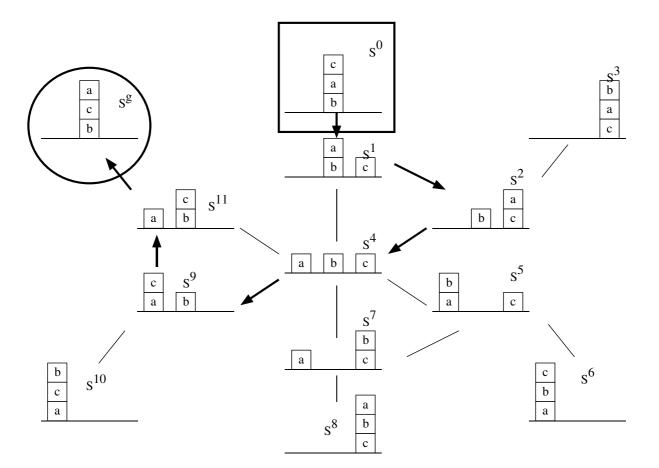


Figure 2: Depth first search and suggestion 1.

## Suggestion 1:

if a block is in final position, do not move it.

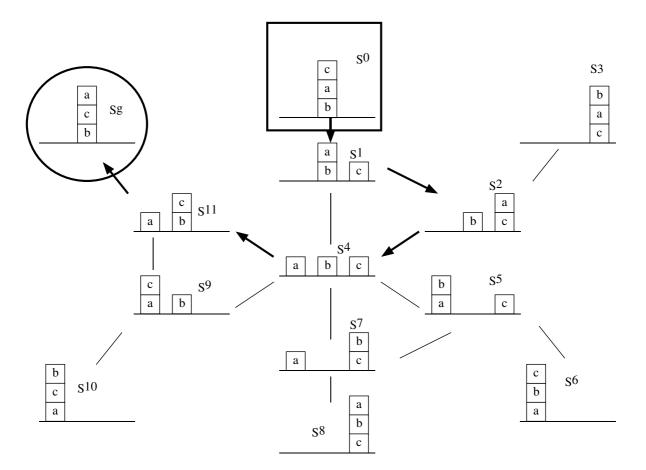


Figure 3: Depth first search, suggestion 1 and 2.

## Suggestion 2:

if any block can be oved to final position, this should be done before any other type of move.

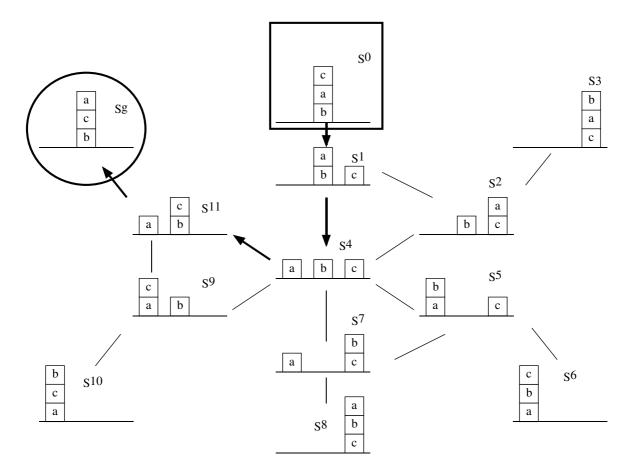


Figure 4: Depth first search, suggestion 1, 2 and 3.

## Suggestion 3:

if there is no block that can be moved to final position, and there is a block that is above a block it ought to be above but it is not in final position, put it on the table.

### Initial configuration

- (1)  $on(C, A, S_0)$
- $(2) \qquad on(A, B, S_0)$
- $(3) \quad on(B, Table, S_0)$

### Goal configuration

- (4)  $on(A, C, S_g)$
- (5)  $on(C, B, S_g)$
- (6)  $on(B, Table, S_g)$

# Unique names axiom

(7)  $Table \neq A \land Table \neq B \land Table \neq C \land A \neq B \land A \neq C \land B \neq C$ 

## Clear

(8) 
$$x = Table \lor \neg \exists y \ on(y, x, s) \to clear(x, s)$$

# Applicable action

$$(9) \quad clear(x,s) \wedge clear(y,s) \wedge x \neq y \wedge x \neq Table \rightarrow applicable(move(x,y),s)$$

### Move action

(10)  $applicable(move(x, y), s) \rightarrow on(x, y, result(move(x, y), s))$ 

## Frame axiom

$$applicable(move(x, y), s) \land on(u, v, s) \land u \neq x \rightarrow$$

$$(11) \qquad on(u, v, result(move(x, y), s))$$

# Final

$$\begin{array}{ll} (12) & on(x,Table,s) \wedge on(x,Table,s_g) \rightarrow final(x,s_g,s) \\ (13) & final(y,s_g,s) \wedge on(x,y,s) \wedge on(x,y,s_g) \rightarrow final(x,s_g,s) \end{array}$$

#### Above

(14) 
$$on(x, y, s) \rightarrow above(x, y, s)$$

(15)  $on(x, z, s) \land above(z, y, s) \rightarrow above(x, y, s)$ 

## Under

(16) 
$$on(x, y, s) \rightarrow under(y, x, s)$$

(17)  $on(x, z, s) \land under(y, z, s) \rightarrow under(y, x, s)$ 

### Action selection rules

Bad move 1: If a block is in final position, do not move it.

(18) 
$$final(x, s_g, s) \rightarrow bad(move(x, y), s, s_g)$$

Safe move 1: If any block can be moved to final position, this should be done before any other type of move.

$$\neg final(x, s_g, s) \land final(x, s_g, result(move(x, y), s)) \rightarrow good(move(x, y), s, s_g)$$
(19)

**Safe move 2:** If there is no block that can be moved to final position, and there is a block that is above a block it ought to be above but it is not in final position, put it on the table.

# Depth First Search

$$\exists s_i (\forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_i)) \land selected(x_1, s_i)) \rightarrow bad(x_1, s, s_g) \\ \exists s_i \forall x \forall y (on(x, y, s_i) \leftrightarrow on(x, y, result(x_2, s)) \land \neg \exists s_i \forall x \forall y (on(x, y, s_i) \leftrightarrow on(x, y, result(x_1, s)) \rightarrow better(x_1, x_2, s, s_g) \\ \exists s_i \exists x_i \exists s_k (\forall x \forall y (on(x, y, result(x_2, s)) \leftrightarrow on(x, y, s_i)) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land \neg \exists s_i \exists x_i \exists s_k (\forall x \forall y (on(x, y, result(x_1, s)) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \leftrightarrow on(x, y, s_k))) \land result(x_i, s_i) = s_k \land \forall x \forall y (on(x, y, s) \land on(x, y, s_k))) \land result(x_i, s_i) = s_k \land x \forall y (on(x, y, s) \land on(x, y, s_k))) \land result(x_i, s_i) = s_k \land x \forall y (on(x, y, s) \land on(x, y, s_k))) \land result(x_i, s_i) = s_k \land x \forall y (on(x, y, s) \land on(x, y, s_k))) \land result(x_i, s_i) = s_k \land x \forall y (on(x, y, s) \land on(x, y, s_k))) \land result(x_i, s_i) = s_$$

# 1 Reasoning

#### Meta-Rules

(24)  $x \neq y \land good(x, s, sg) \rightarrow bad(y, s, sg)$ 

- (25)  $bad(x, s, sg) \to \neg good(x, s, sg)$
- (26)  $\neg \forall x bad(x, s, sg)$
- (27)  $x \neq y \land better(x, y, s, sg) \rightarrow bad(y, s, sg)$

**Consistency:** Find an action that cannot be proved to be bad (see meta-rules) for the current goal and situation.

# 2 Reasoning Strategies

Express reasoning strategies, proof schemas.

Knowledge handling rules: three main components.

- 1. the class of facts or goal the rule can be used to know about
- 2. the inference operator that should be applied
- 3. the class of facts that act as hypotheses for the inference

Can be composed like mathematical functions, and combined procedurally like LISP programs.

ON- $NOW(S) \equiv CIRC(on(x, y, S) : NOW, 7)$ 1. ON- $GOAL(S_g) \equiv CIRC(on(x, y, S_g) : GOAL, 7)$ 2. **3.**  $DED(\forall x(on(x, y, S) \leftrightarrow on(x, y, S_g)) : ON-NOW(S), ON-GOAL(S_g))$ 4.  $APPLICABLE(S) \equiv CIRC(applicable(x, S): ON-NOW(S), 8, 9, 7)$ **5.**  $DED(applicable(x, S) \land \forall y(applicable(y, S) \rightarrow y = x) :$ APPLICABLE(S))  $NEXT(S, X) \equiv CIRC(on(z, y, result(X, S)))$ : 6. APPLICABLE(S), ON-NOW(S), 10, 11, 7)7.  $FINAL-NOW(S, Sg) \equiv CIRC(final(x, S_g, S): ON-NOW(S)),$  $ON-GOAL(S_{g}), 7, 12, 13)$ 8. ON- $NEXT(S) \equiv CIRC(on(z, y, result(x, S)))$ : APPLICABLE(S), ON-NOW(S), 10, 11, 7)  $FINAL-NEXT(S, S_a) \equiv CIRC(final(z, S_a, result(x, S))): ON-NEXT(S),$ 9.  $ON-GOAL(S_g), 7, 12, 13)$ **10.**  $DED(good(x, S, S_g) : FINAL-NOW(S, S_g), FINAL-NEXT(S, S_g),$ ON-NOW(S), 19, 14, 15, 20, 16, 17, ??) 11. ON- $PAST(S) \equiv CIRC(on(x, y, s) : PAST(S))$  $SELECTED(S) \equiv CIRC(selected(x, s): PAST(S))$ 12.  $BADS(S, S_q) \equiv CIRC(bad(x, S, S_q): ON-PAST(S), ON-NOW(S)),$ 13.  $ON-NEXT(S), FINAL-NOW(S, S_q), FINAL-NEXT(S, S_q),$ SELECTED(S), 18, ??, ??, ??, 21, 22, 23, 27, 7)14.  $DED(\neg bad(x, S, S_a) : BADS(S, S_a))$ 

**Logical Spreadsheet** Knowledge handling rules could be processed by a logical spreadsheet

- two dimensional table = (formula schemas  $\times$  instances)
- formula schemas: axioms, intermediate results and conclussions
- intermediate results, expressed as knowledge handling rules, should be obtained by composition and combination of inference operations
- should allow building up proofs in a easy way
  - outlining their main steps and refining them progressively (top down)
  - building proofs out of simple initial results by inference composition and combination (bottom up)
- should access different theorem provers combining their functionalities

# Elaboration: move tower

### Tower (composite object)

(28)  $tower(x_1, \ldots, x_n, s) \leftrightarrow \forall i (1 \le i < n \to on(x_{i+1}, x_i, s))$ 

Note: block is a particular case.

### On

(29)  $on(t_1, t_2, s) \leftrightarrow on(bottom(t_1), top(t_2), s)$ 

Note: for blocks bottom(x) = top(x) = x

### Top

(30)  $tower(x_1,\ldots,x_n,s) \to x_n = top(x_1,\ldots,x_n,s)$ 

### Bottom

(31)  $tower(x_1,\ldots,x_n,s) \to x_1 = bottom(x_1,\ldots,x_n,s)$ 

# Postponability as problem simplification

(32)  $postponable(g, problem) \rightarrow improves(problem, adjoin(problem - g, g))$ 

**Postponable move 1:** If a block is in final position, do not move it.

**Postponable move 2:** If a block is in final position, one need not think about putting anything on that block until it can be put in final position.

**Postponable move 2:** If a block is on the table but not in final position, one need not think about moving or putting anything on it until it can be put in final position.

**Simplification 1:** Remove all finished towers of blocks in final position.

**Simplification 2:** Remove all clear blocks on the table which are not in final position.

**Simplification 3:** Replace any unfinished tower of blocks in final position by a single block on the table and in final position.

**Simplification 1:** Replace any partially finished tower by a single block.

### Partially finished tower

(33) 
$$partially - finished - tower(x_1, \dots, x_n, s, sg) \leftrightarrow$$
  
 $\forall i(1 \le i < n \to on(x_{i+1}, x_i, s) \land on(x_{i+1}, x_i, sg))$ 

# Safe moves

We need at most two moves to put a block in final position.

- 1. Clear final position by moving tower above it to the table.
- 2. Put block in final position by moving tower above it (including it) to final position.

Strategy: build towers bottom-up.

### Can be improved:

- 1. some blocks can be put in final position by a single move
- 2. some blocks cannot be put in final position without their final position being cleared up